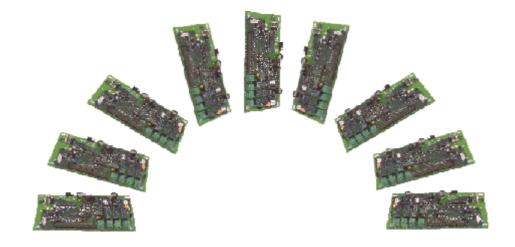
## VACON CX/CXL/CXS FREQUENCY CONVERTERS



# I/O-expander board installation manual (Vacon CX/CXL-range)

Subject to changes without notice.



FOR SMOOTH CONTROL

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### 1 GENERAL

### 1.1 Vacon CX100OPT

The available I/O can be increased by using the Vacon CX100OPT I/O-expander board:

- 5 digital inputs (standard signals)
- 2 analogue inputs (standard signals)
- 3 relay outputs (standard signals)
- analogue output (programmable in "Five in One+" Application)
- thermistor input (can be directly connected to the motor thermistors to monitor the motor temperature)
- encoder input

Typical use: Closed Loop Vector Control

### 1.2 Vacon CX101OPT

The available I/O can be increased by using the Vacon CX101OPT I/O-expander board:

- 5 digital inputs (standard signals)
- relay output (standard signal)
- thermistor input (can be directly connected to the motor thermistors to monitor the motor temperature)

Typical use: thermistor input required

### 1.3 Vacon CX102OPT

The available I/O can be increased by using the Vacon CX102OPT I/O-expander board:

- 5 digital inputs (standard signals)
- 2 analogue inputs (standard signals)
- 3 relay outputs (standard signals)
- analogue output (programmable in "Five in One+" Application)
- thermistor input (can be directly connected to the motor thermistors to monitor the motor temperature)
- encoder input

Typical use: Closed Loop Vector Control

### 1.4 Vacon CX103OPT

The available I/O can be increased by using the Vacon CX103OPT I/O-expander board:

- 5 digital inputs (standard signals)
- 3 relay outputs (standard signals)
- analogue output (programmable in "Five in One+" Application)
- thermistor input (can be directly connected to the motor thermistors to monitor the motor temperature)

Typical use: thermistor input and additional analogue output required

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### 1.5 Vacon fieldbus boards

Vacon fieldbus boards can be installed in the CX/CXL range frequency converters like the I/O-expander boards, except the LonWorks board. The needed information to install/commission fieldbus boards can be found in the respective fieldbus manual.

Page 3 (10)

- Vacon CX 200OPT (Interbus-S)
- Vacon CX 201OPT (Modbus)
- Vacon CX 202OPT (Profibus-DP)
- Vacon CX 203OPT (LonWorks)

The LonWorks fieldbus board (Vacon CX 203OPT) must be installed in a separate external option board box. More information can be found in the I/O-expander board installation manual for CXS range.

### 2 SPECIFICATIONS

Safety		Fulfills EN50178, C-UL and EN60204-1 standards			
Control	Analogue voltage, input	0—± 10 V, R <sub>i</sub> ≥ 200 k $Ω$			
connections	Analogue current, input	$O(4)$ —20 mA, R <sub>i</sub> = 250 $\Omega$			
	Digital input	24 V: "0" $\leq$ 10 V, "1" $\geq$ 18 V, $R_i > 5$ k $\Omega$			
	Aux. voltage	24 V (±20%), max. 50 mA			
	Reference voltage	10 V ±3 %, max. 10 mA			
	Analogue current, output Analogue voltage, output				
	Relay output	Max. switching voltage:  Max. switching load:  8A / 24 V DC  0,4 A / 300 V DC  2 kVA / 250 V AC  Max. continuous load:  2 A rms			
	Thermistor input	$R_{trip} = 4.7 \text{ k}\Omega$			
	Encoder input	24 V: "0" $\leq$ 10 V, "1" $\geq$ 18 V, $R_i = 2.2 \text{ k}\Omega$			
		5 V: "0" $\leq$ 2 V, "1" $\geq$ 3 V, R <sub>i</sub> = 330 $\Omega$			

Table 2-1 Specifications.

(All the control connections are not found on every I/O-expander board, for more specific information see Chapters 1 and 4.)

The control connections are isolated from the mains potential and the I/O ground is connected to the frame of the inverter via a 1-M $\Omega$  resistor and 4,7-nF capacitor\*). The control I/O ground can be connected directly to the frame of the inverter by changing the position of jumper X4 (GND ON/OFF) to ON-position. Digital inputs and relay outputs are also isolated from the I/O ground.

\*) Default value (X4 is GND OFF- position).

### NOTE!



Internal components and circuit boards (except for the isolated I/O terminals) are at mains potential when the frequency converter is connected to the mains. This voltage is extremely dangerous and may cause death or severe injury if you come in contact with it.

The control I/O terminals are isolated from the mains potential, but the relay outputs and other I/O's may have a dangerous voltage connected even if the power is disconnected from the frequency converter.

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### 3 INSTALLATION

### 3.1. General

Check that your have received all the required parts (figure 3-1):

- I/O-expander board (1) (check that the typecode corresponds to your order)
- protection foil (2)
- power cable (3) (4-pole)
- data cable (4) (10-pole)
- 20-pole I/O-wire (grey wire) (6)
- 2 to 8 black wires depending on I/O-expander board and application (7)
- terminal strips: 2 times 4-pole, 2 times 12-pole and 2 gable ends (8)
- stickers for I/O-terminal, I/O-board and I/O-expander board (8)
- screw (5) (for earthing), cable ties (9)

Note: The I/O-expander board package includes parts 1 - 5 for the power sizes Vacon 2.2 CX\_ /CXL\_ - Vacon 90 CX\_/CXL\_.

For the bigger power sizes the parts 6 - 9 need to be ordered separately (type code MOCXM8M12KIT).

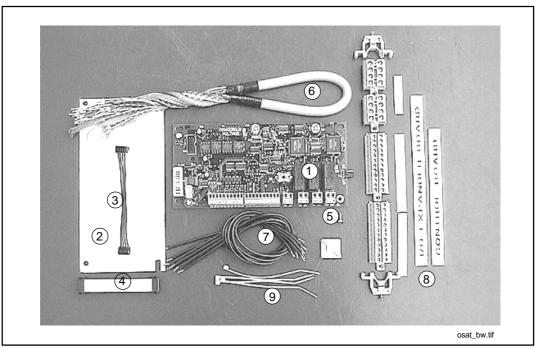


Figure 3-1. I/O-expander board parts.

If the delivery does not match your order, please contact your supplier immediately. Before doing any commissioning carefully read the safety instructions in "USER'S MANUAL VACON CX/CXL/CXS Frequency converters", Chapter 1, SAFETY.



Disconnect the frequency converter from the mains. NOTE: also the control circuits! Wait further 5 minutes before opening the cover of the frequency converter. Verify by measuring that the frequency converter is safe to touch.

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### 3.2 INSTALLATION

The I/O-expander board should be installed above the existing control board location inside the frequency converter (see table 3-2) as described below:

Remove the control panel, control panel base (4 screws) and the jumper X4 from the control board.

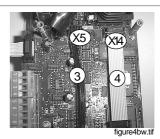






Connect the power cable (3) to control board terminal X5. (The power cable can also be connected to terminal X6 terminal, if the power cable from the power board is connected to terminal X5.)

Connect the data cable (4) to control board terminal X14. Bend the data cable into an "S-curve" as far as possible from the power board.



Remove the protection foil (2) of the plastic board and mount the plastic board above the control board. Make sure that the plastic board is correctly placed.

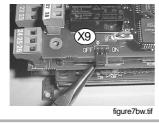


Mount the I/O-expander board on the plastic board by the larger holes and "push" it into the right position in the narrow position of the holes. Check that the I/O-expander board is installed correctly. If you have difficulties mounting the plastic board and I/O-expander board, slightly bend the regulator A4 and capacitor C59 of the control board.

6 Connect the power cable to I/O-expander board terminal X2 and data cable to terminal X14.



Install the jumper removed from terminal X4 of the control board on terminal X9 of the I/O-expander board. Note: the jumper can be connected in ON or OFF position, see Vacon CX/CXL/CXS User's Manual, Chapter 6.2.2. Tighten up the earthing screw (5).



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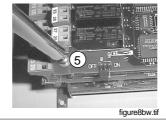


Table 3-2. I/O-expander board installation (continues ...).

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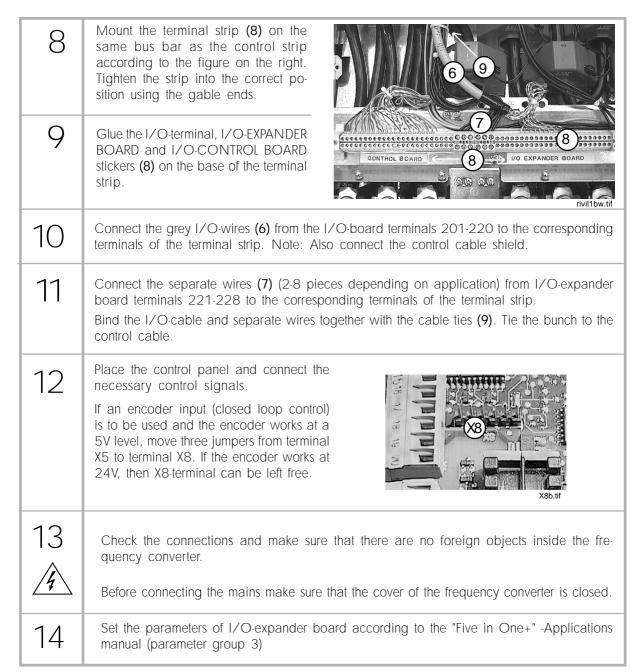


Table 3-2. I/O-expander board installation.

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### 4 CONTROL CONNECTIONS

### 4.1 Vacon CX100OPT

	Termi	nal	Signal	Description
	201	+10V <sub>ref</sub>	Reference output	Voltage for a potentiometer, etc.
	202	U <sub>in</sub> +	Analogue input, voltage range 0—10 V DC	Not in use
	203	GND	I/O ground	Ground for reference and controls
	204	$I_{in}^{+}$	Analogue input, current	Not in use
	205	I <sub>in</sub> -	range 0—20 mA	
	206	+24V	Control voltage output	Voltage for switches, etc. max. 50 mA
;	207	GND	I/O ground	Ground for reference and controls
¦ '—-[	208	avc	Common for DIC1-DIC5	Connect to GND or + 24 V
	209	DIC1	External fault (closing contact)	Contact open = no fault Contact closed = fault
	210	DIC2	Run disable	Cont. open = start of motor enabled Cont. closed= start of motor disabled
	211	DIC3	Acceler. / Decel. time selection	Contact open = time 1 selected Contact closed = time 2 selected
<del> </del>	212	DIC4	Jogging speed selection	Contact open = no action Contact closed = jogging speed
	213	DIC5	Fault reset	Contact open = no action Contact closed = fault reset
/ <del>-</del>	214	DI6A+	Pulse input A	
<u></u>	215	DI6A-	(differential input)	
	216 217	DI7B+ DI7B-	Pulse input B (differential input)	90 degrees phase shift compared to pulse input A
<u> </u>	218 219	DI8Z+	Pulse input C (differential input)	one pulse per one revolution
	220	I <sub>out</sub> +	Analogue output 0—20 mA/R $_{\rm l}$ max. 500 $\Omega$	Programmable (Motor current as default value)
Signal from — —	221	TI+	Thermistor input	
motor thermistors	222	TI-		
*)	223	RO3/1	/ Relay output 3	READY
	224	RO3/2		
	225	RO4/1	Relay output 4	RUN
	226	RO4/2		
	227	RO5/1	Relay output 5	FAULT
	228	RO5/2		

Figure 4-1 Control connections of Vacon CX100OPT.

\*) NOTE! Thermistor input (terminals 221 and 222) must be shorted if not used.

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### 4.2 Vacon CX101OPT

	Terminal		Signal	Description
	206	+24V	Control voltage output	Voltage for switches, etc. max. 50 mA
i $\square$	207	GND	I/O ground	Ground for reference and controls
i _	208	avc	Common for DIC1-DIC5	Connect to GND or + 24 V
	209	DIC1	External fault (closing contact)	Contact open = no fault Contact closed = fault
	210	DIC2	Run disable	Cont. open = start of motor enabled Cont. closed= start of motor disabled
	211	DIC3	Acceler. / Decel. time selection	Contact open = time 1 selected Contact closed = time 2 selected
	212	DIC4	Jogging speed selection	Contact open = no action Contact closed = jogging speed
	213	DIC5	Fault reset	Contact open = no action Contact closed = fault reset
	214	N.C.		Not connected
	215	N.C.		Not connected
Signal from — —	221	TI+	Thermistor input	
motor thermistors — — *)	222	TI+		
)				
	225	RO4/1	Relay output 4	RUN
	226	RO4/2		

Figure 4-2 Control connections of Vacon CX101OPT.

\*) NOTE! Thermistor input (terminals 221 and 222) must be shorted if not used.

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## 4.3 Vacon CX102OPT

	Term	inal	Signal	Description	
	201	+10V <sub>ref</sub>	Reference output	Voltage for a potentiometer, etc.	
	202	U <sub>in</sub> +	Analogue input, voltage range 0—10 V DC	Not in use	
	203	GND	I/O ground	Ground for reference and controls	
	204	U <sub>in</sub> +	Analogue input, voltage	Not in use	
	205	U <sub>in</sub> -	range 0—10 V DC		
	206	+24V	Control voltage output  Voltage for switches, etc. max. 5  I/O ground  Ground for reference and control  Common for DIC1-DIC5  Connect to GND or + 24 V		
<u> </u>	207	GND			
<u> </u>	208	avc			
<u> </u>	209	DIC1	External fault (closing contact)	Contact open = no fault Contact closed = fault	
	210	DIC2	Run disable	Cont. open = start of motor enabled Cont. closed= start of motor disabled	
	211	DIC3	Acceler. / Decel. time selection	Contact open = time 1 selected Contact closed = time 2 selected	
<u> </u>	212	DIC4	Jogging speed selection	Contact open = no action Contact closed = jogging speed	
L_/	213	DIC5	Fault reset	Contact open = no action Contact closed = fault reset	
	214	DI6A+	Pulse input A		
(Enco-)	<b>-</b> 215	DI6A-	(differential input)		
der	216 217	DI7B+ DI7B-	Pulse input B (differential input)	90 degrees phase shift compared to pulse input A	
	218	DO1	Encoder direction output	to paise input A	
	219	DO2	Encoder divider 1/64 output		
	220	U <sub>out</sub> +	Analogue output $0-10 \text{ V DC/R}_1 \ge 1 \text{ k}\Omega$	Programmable (Motor voltage as default value)	
Signal from — -	221	TI+	Thermistor input		
motor thermistors	222	TI-			
*)	223	RO3/1		Relay output 3 READY	
	224	RO3/2			
	225	RO4/1		Relay output 4 RUN	
	226	RO4/2			
	227 228	RO5/1 RO5/2		Relay output 5 FAULT	
		1	<u> </u>		

Figure 4-3 Control connections of Vacon CX102OPT.

\*) NOTE! Thermistor input (terminals 221 and 222) must be shorted if not used.

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### 4.4 Vacon CX103OPT

	Terminal		Signal	Description
		+24V	Control voltage output	Voltage for switches, etc. max. 50 mA
<u> </u>	207	GND	I/O ground	Ground for reference and controls
	208	avc	Common for DIC1-DIC5	Connect to GND or + 24 V
	209	DIC1	External fault (closing contact)	Contact open = no fault Contact closed = fault
	210	DIC2	Run disable	Cont.open = start of motor enabled Cont. closed= start of motor disabled
	211	DIC3	Acceler. / Decel. time selection	Contact open = time 1 selected Contact closed = time 2 selected
  -/	212	DIC4	Jogging speed selection	Contact open = no action Contact closed = jogging speed
	213	DIC5	Fault reset	Contact open = no action Contact closed = fault reset
	214	GND	I/O ground	
	215	l <sub>out</sub> +	Analogue output 0—20 mA/ $R_L$ max. 500 $\Omega$	Programmable (Motor current as default value)
	221	TI+	Thermistor input	
Signal from — — — motor thermistors — —	221	TI-	Thermistor input	
*)	223 224 225	RO3/1	Relay output 3	READY
		RO3/2	- Relay output o	KENDT
		RO4/1		RUN
	226	RO4/2		
	227 228	RO5/1	Relay output 5	FAULT
		RO5/2		

Figure 4-3 Control connections of Vacon CX103OPT.

\*) NOTE! Thermistor input (terminals 221 and 222) must be shorted if not used.

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