

RTEX

**EtherCAT** 

## **Motion Controller**

**GM1** SERIES







PLC + Motion + Communication All - in - one

## IN Better Solution



RTEX type



EtherCAT type

## PLC + Motion + Communication

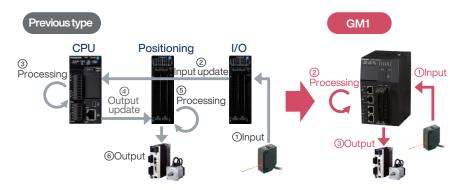
### **Integrate PLC and motion**

## Standardization of PLC programming

Enhanced communication between the upper level and the device

#### Integrate PLC and motion

High speed motion control Fastest cycle 500µs Multitask control by function aggregation



#### **Motion control**

- Positioning / Speed control / Torque control
- Cam synchronization,
   Gear synchronization, CNC control

#### Multitask control

- · High speed motion control
- Display / Device / Upper communication
- Data processing

#### Standardization of PLC programming

## Break away from manufacturer-dependent programming

Programming: IEC61131-3 standard compliant, PLCopen Supports 6 languages: LD / ST / FBD / SFC / IL / CFC Componentization by library function Supports object orientation

#### **GM Programmer**



\*It can be downloaded free of charge from our website.

SCADA

#### Enhanced communication between the upper level and the device

#### Supports various network protocols

#### Communication with upper levels

OPC UA Server FTP Server

#### Communication between devices

Ethernet/IP Modbus Codesys V3 communication









HMI



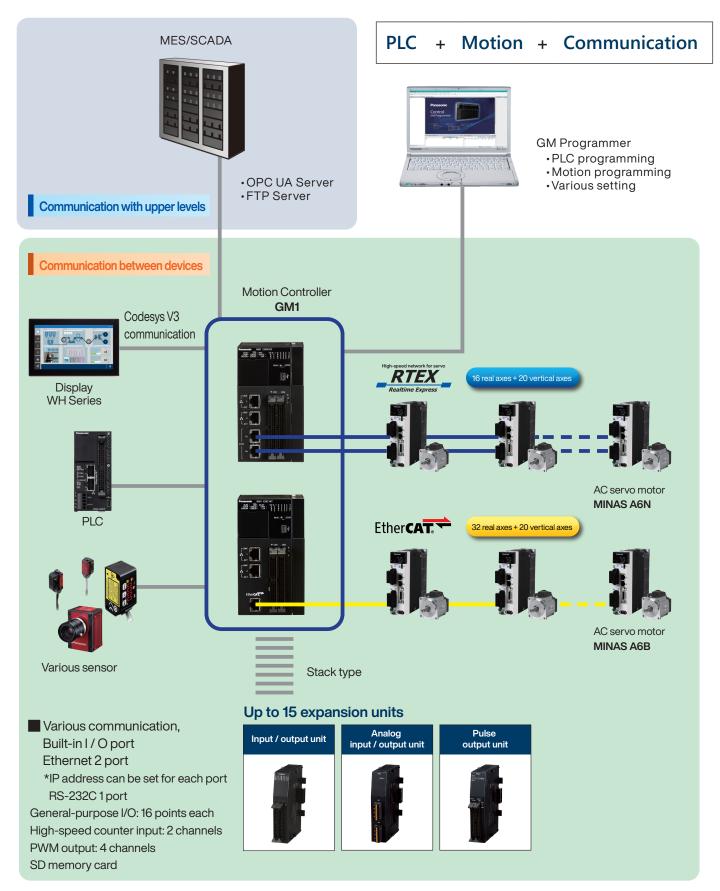


**FRP** 

Various sensor

PI (

## System configuration



- \* Realtime Express and RTEX are registered trademarks of Panasonic Holdings Corporation. Realtime Express is a high-speed and synchronous motion network exclusively developed by our company.
- \* The EtherCAT is a registered trademark of patented technology licensed from Beckhoff Automation GmbH in Germany.

#### **Motion**

#### Various motion control is possible

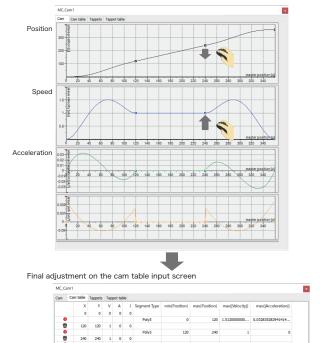
- Motion and input / output control with the fastest control cycle of 500 µs (including expansion unit)
- · Motion control that can be configured with 3 elements of real axis / virtual axis / encoder axis
- Not only basic single axis control (position / speed / torque control) but also multi-axis synchronous control (gear cycle, cam cycle, interpolation control, CNC control) is possible.

#### You can freely generate a cam curve with the cam editor

- · Adjustment is possible while looking at the position, speed, and acceleration curve of the slave axis using the cam editor.
- Timing adjustment with other devices according to the master position is possible (tappet function)

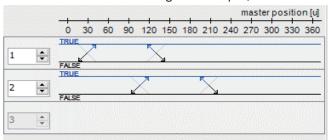
#### Cam editor

Connect points with a linear or degree 5 polynomial



#### **Tappet**

Set ON / OFF timing for IO output, etc.



	Track ID	X	positive pass	negative pas
•	1			
W		30	switch ON	switch OFF
W		130.63711911357342	switch OFF	switch ON
0	2			
W		106.70360110803324	switch ON	switch OFF
W		209.41828254847644	switch OFF	switch ON
•				

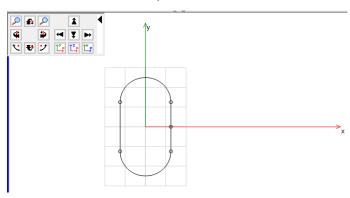
#### Trajectory generation by G-code description and 3-axis synchronous control are possible with CNC editor

- Control according to the application is possible from interpolation control to complicated trajectory control.
- In-program variable import, repeat processing, coordinate conversion, and smoothing are possible by G-code description.

#### G-code editor

```
1
    N00 G99 X10 Y0
2
    N01 G01 X10 Y10
    N02 G03 R10 X-10 Y10
3
4
    N03 G01 X-10 Y-10
5
    N04 G03 R10 X10 Y-10
6
    N05 G01 X10 Y0
```

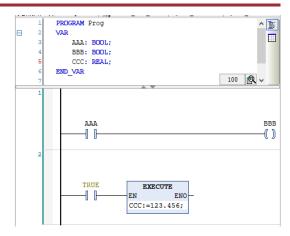
#### Graphic editor



#### **PLC**

#### Achieve object-oriented programming

- Divided implementation by POU (program configuration unit)
- Program part, function part (FB, FUN), variable definition part (structure, enumeration, union)
- FB methods and inheritance (equivalent to class concept), interfaces available
- Realization of componentization by library function



#### Project data management is possible

#### **New function**

#### **Recipe manager function**

- Management of product type data
- Backup / restore of retained data

RecipeData 🗶	Q RecipeData X								
Variable	Type	Name	Comment	Minimal Value	Maximal Value	Current Value	InitialRecipe	Rcp1	Rcp2
GVL.stRecipesData.int_val[0]	INT	Width		0	10		0	0	0
GVL.stRedpesData.int_val[1]	INT	Height		0	100		1	1	1
GVL.stRedpesData.int_val[2]	INT	Weight		0	99		2	2	2
GVL.stRecipesData.int_val[3]	INT	Length1		0	10000		3	3	3
GVL.stRecipesData.int_val[4]	INT	Length2		0	10000		4	4	4
GVL.stRecipesData.int_val[5]	INT	Length3		0	10000		5	5	5
GVL.stRecipesData.int_val[6]	INT						6	6	6
GVL.stRecipesData.int_val[7]	INT						7	7	7
GVL.stRecipesData.int_val[8]	INT						8	8	8
GVL.stRecipesData.int_val[9]	INT						9	9	9

#### **Project management function**

By operating the main unit

- Project backup to SD
- Project restore from SD



#### Communication

#### Communication settings can be set easily

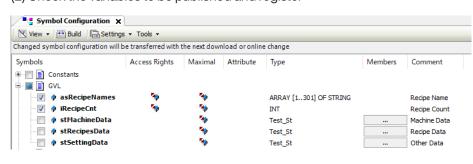
**New function** 

Can be easily registered to the display or OPC UA server Variable list can be generated in XML file

(1) Enable / disable OPC UA server



(2) Check the variables to be published and register



## **Specifications**

#### ■ GM1 Controller unit common specifications



RTEX type AGM1CSRX16T



EtherCAT type AGM1CSEC16T AGM1CSEC16P

Item	Specifications
Rated voltage	24 V DC
Operating voltage range	20.4 to 28.8 V DC
Allowable momentary power failure time	10 ms
Operating ambient temperature	0 to +55 ℃
Storage ambient temperature	-40 to +70 °C
Operating ambient humidity	10 to 95 %RH (at +25 °C, no condensation or icing)
Storage ambient humidity	10 to 95 %RH (at +25 °C, no condensation or icing)
Vibration resistance (Leakage current 5 mA)	500 V AC for one minute (Note 1)
Insulation resistance (Test voltage 500 V DC)	100 MΩ or more (Note 1)
Vibration resistance	Compliant with JIS B 3502, IEC 61131-2 5 to 8.4 Hz, half amplitude 3.5 mm 8.4 to 150 Hz acceleration 9.8 m/s <sup>2</sup> 10 sweeps each in X, Y and Z directions (1 octave/min)
Shock resistance	Compliant with JIS B 3502, IEC 61131-2 147 m/s², 3 times each in the X, Y, Z directions
Noise resistance	$1000\ V$ [P-P]with pulse widths of 1 $\mu s$ and 50 ns (using a noise simulator) (Power supply terminal)
Atmosphere	Free of corrosive gases No excessive dust
European EU standards	EMC : EN 61131-2 RoHS : EN IEC 63000
Overvoltage category	Category II
Pollution degree	2

(Note 1): For details about the Dielectric strength or the Insulation resistance, check on the specifications of each product.

#### Specifications of the USB Port

Item	Specifications
Standard	USB2.0 Fullspeed
Connector shape	USB miniB type

#### Specifications of the COM Port (RS-232C)

Item		Specifications
No. of channels		1
Physical layer		RS-232C, three-wire system (non-isolated)
Transmission distance		MAX. 15 m
Communication mode		1:1 communication
Communication method		Half-duplex transmission
Transmission line		Multicore shielded wire
Baud rate		9600 / 19200 / 38400 / 57600 / 115200 bps
	Data length	7 bit / 8 bit
	Parity	None, odd, even
Communication format	Stop bit	1bit/2bit
	Start code	None
	End code	None
Connector shape		Removable terminal block (5-pin)

#### Specifications of the LAN Port

Item		Specifications
Number of ports		2
Communication interface		Ethernet 100BASE-TX / 10BASE-T
Baud rate		100 Mbps / 10 Mbps, automatic negotiation
Max. segment length		100 m (Note 1)
Man distance between and a		100BASE-TX 2 segments
Max. distance between nodes		10BASE-T 5 segments
Communication cable		Shielded twisted pair (TIA/EIA-568B CAT5e or higher)
Communication protocol		TCP/IP UDP
	LAN1	Maximum 16 units (System connection: 1 unit, user connection: 15 units)
No. of simultaneous connections	LAN2	Max. 32 units, general-purpose: 16 units A cycle restriction is applied depending on the total number of connections.
Communication method		Full-duplex / half-duplex communication
TCP/IP protocol		TCP/IP compliant (IPV4)
Functions		Modifying or holding the network settings (IP, Subnet, Gateway)     Possible to set the same or different networks between Ethernet ports.     Routing between Ethernet ports is not performed.
	LINK	Lit when connection is established with the device on the Ethernet network.
LED display	ACT	Flashes when some communication is performed such as transmitting commands and responses with the devices with established connections.

(Note 1): The standards cite 100m as the maximum, but noise resistance measures such as attaching a ferrite core may be necessary in some cases, depending on the usage environment. Also, it is recommended to position a hub near the control board, and limit the length within 10m.

#### Specifications of the RTEX/EtherCAT

Item	Specifications (RTEX type)	Specifications (EtherCAT type)
Baud rate	100 Mbps	
Physical layer	100BASE-TX full duplex (IEEE 802.3u)	
Cable	Shielded twisted pair (TIA/EIA-568B CAT5e or higher)	
Topology	Ring	Daisy chain (No branching)
Insulation method	Pulse transformer	
Connector	8-pin RJ45	
Maximum cable length	Between nodes: 100 m, total length: 200 m	
Transmission distance		Between nodes: Max. 100 m
Communication cycle	500 µs to 2 ms	500 µs or more
Command update period	500 µs to 4 ms	
Operation command	Profile position, cyclic position / speed / torque	
Number of connectable axes	16 real axes, 20 vertical axes (Total 36 axes)	32 real axes, 20 vertical axes (Total 52 axes)

#### **High-speed Counter Input Specifications**

-9p				
	Specifications			
lham	Input A, B, Z signals			
Item	24 V DC	5 V DC		
	24 V DC	Open collector connection	Line driver connection	
Insulation method	Optical coupler			
Rated input voltage	12 V DC to 24 V DC	5 V DC	Facility along the AMOCI CO1	
Operating voltage range	10.8 V DC to 26.4 V DC	3.5 V DC to 5.5 V DC	Equivalent to AM26LS31	
Input points per common	Independent common for each point			
Min. ON voltage / Min. ON current	10 V DC / 4 mA	3VDC/4mA		
Max. OFF voltage / Max. OFF current	2 V DC / 2 mA	1 V DC / 0.5 mA		
Input impedance	Approx. 3.9 kΩ	Approx. 560 Ω		
Operating mode indicator	6-point LED display			

#### Input Specifications

nput opcomodations			
Item		Specifications	
Insulation method		Optical coupler	
Rated input voltage		24 V DC	
Rated input current		Approx. 3 mA (at 24 V DC)	
Input impedance		Approx. 6.8 kΩ	
Operating voltage range		21.6 to 26.4 V DC	
Min. ON voltage / Min. ON current		19.2 V / 6 mA	
Max. OFF voltage / Max. OFF curre	nt	2.4 V / 1 m A	
Barrana	OFF→ON	135 µs max. (Possible to change by using the input time constant selection function)	
Response time	ON→OFF	135 µs max. (Possible to change by using the input time constant selection function)	
Input points per common		16 points/1 common	
Operating mode indicator		16-point LED display (Lit when ON, SW selection)	
External connection method		Connector connection (Compliant with the MIL standard, 40P)	

#### **Output Specifications**

urbut opecimications					
Item		Specifications (sink type)	Specifications (source type)		
Insulation method		Optical coupler	Optical coupler		
Output type		NPN open collector	PNP open collector		
Rated load voltage		5 to 24 V DC	24 V DC		
Allowable load voltage range		4.75 to 26.4 V DC	21.6 to 26.4 V DC		
Max. load current		0.3 A			
Common restrictions		3.2 A/common			
Max. inrush current		1.0 A	10 A		
OFF state leakage current		1μA or less	2 µA or less		
ON state max. voltage drop		0.7 V or less	0.7 V or less		
Descriptions discre	OFF→ON	6 µs or less (at an ambient temperature of 25°C)			
Response time	ON→OFF	15 µs or less (at an ambient temperature of 25°C)			
External connection method	Voltage	4.75 to 26.4 V DC	21.6 to 26.4 V DC		
External connection method	Current	35 mA/common (at 24 V)	30 mA/common (at 24 V)		
Surge absorber		Zener diode			
Short-circuit protection		Provided (to automatically protect every eight points) (Note 1)			
Input points per common		16 points/1 common			
Operating mode indicator		16-point LED display (Lit when ON, SW selection)	16-point LED display (Lit when ON, SW selection)		
External connection method		Connector connection (Compliant with the MIL sta	Connector connection (Compliant with the MIL standard, 40P)		

 $(Note \ 1): When \ the \ maximum \ in rush \ current \ is \ exceeded, eight \ output \ points \ in \ the \ same \ protection \ block \ are \ turned \ OFF \ simultaneously.$ 

## Specifications

#### Input Unit Specifications



AGM1X64D2

Item		Specifications	
Insulation method		Optical coupler	
Rated input voltage		24 V DC	
Rated input current		Approx. 2.7 mA (at 24 V DC)	
Input impedance		Αρρτοχ. 6.8 kΩ	
Operating voltage range		20.4 to 26.4 V DC	
Min. ON voltage / Min. ON current		19.2 V / 2.5 mA	
Max. OFF voltage / N	Лах. OFF current	5 V / 1.5 mA	
D	OFF→ON	0.2 ms max. (Possible to change by using the input time constant selection function)	
Response time	ON→OFF	0.2 ms max. (Possible to change by using the input time constant selection function)	
Input points per common		32 points/1 common	
Operating mode indicator		Operating mode indicator: 32-point LED display (Lit when ON, SW selection)	
External connection method		Connector connection (Compliant with the MIL standard, 40P, two pieces used)	

#### **■**Output Unit Specifications



AGM1Y64T AGM1Y64P

Item		Specifications (sink type)	Specifications (source type)		
Insulation method		Optical coupler	Optical coupler		
Output type		NPN open collector	PNP open collector		
Rated load voltage		5 to 24 V DC	•		
Allowable load voltage r	ange	4.75 to 26.4 V DC			
Max. load current		0.3 A (20.4 to 26.4 V DC), 30 mA (4.75 V DC)			
Common restrictions		3.2 A/common			
Max. inrush current		0.6 A			
OFF state leakage current		1μA or less	1μA or less		
ON state max. voltage drop		0.5 V or less	0.5 V or less		
D	OFF→ON	0.1 ms or less (Load current: 2 mA or more)	0.1 ms or less (Load current: 2 mA or more)		
Response time	ON→OFF	0.3 ms or less (Load current: 2 mA or more)	0.5 ms or less (Load current: 2 mA or more)		
E to color to the	Voltage	4.75 to 26.4 V DC			
External power supply	Current	70 mA/common (at 24 V)	90 mA/common (at 24 V)		
Surge absorber		Zener diode	Zener diode		
Short-circuit protection		None	None		
Input points per common		32 points/1 common	32 points/1 common		
Operating mode indicator		32-point LED display (Lit when ON, SW selection	32-point LED display (Lit when ON, SW selection)		
External connection method		Connector connection (Compliant with the MIL	Connector connection (Compliant with the MIL standard, 40P, two pieces used)		

#### ■ Input / Output unit Specifications



AGM1XY64D2T AGM1XY64D2P

Item			Specifications (sink type)	Specifications (source type)		
	Insulation method		Optical coupler			
	Rated input voltage		24 V DC			
	Rated input current		Approx. 2.7 mA (at 24 V DC)			
	Input impedance		Approx. 6.8 kΩ			
Input speci-	Operating voltage	range	20.4 to 26.4 V DC			
fications	Min. ON voltage / I	Min. ON current	19.2 V / 2.5 mA			
	Max. OFF voltage	/ Max. OFF current	5 V / 1.5 mA			
	Danas dinas	OFF→ON	0.2 ms max. (Possible to change by using the inp	ut time constant selection function)		
	Response time	ON→OFF	0.2 ms max. (Possible to change by using the input time constant selection function)			
	Input points per common		32 points/1 common			
	Insulation method		Optical coupler			
	Output type		NPN open collector	PNP open collector		
	Rated load voltage		5 to 24 V DC			
	Allowable load voltage range		4.75 to 26.4 V DC			
	Max. load current		0.3 A (20.4 to 26.4 V DC), 30 mA (4.75 V DC)			
	Common restriction	ons	3.2 A/common			
	Max. inrush currer	nt	0.6 A			
Output speci-	OFF state leakage	current	1μA or less			
fications	ON state max. volt	age drop	0.5 V or less			
	Response time	OFF→ON	0.1 ms or less (Load current: 2 mA or more)			
	nesponse time	ON→OFF	0.3 ms or less (Load current: 2 mA or more)	0.5 ms or less (Load current: 2 mA or more)		
	External power	Voltage	4.75 to 26.4 V DC			
	supply	Current	70 mA/common (at 24 V)	90 mA/common (at 24 V)		
	Surge absorber		Zener diode			
	Short-circuit protection		None			
	Input points per common		32 points/1 common			
Operating mode indicator			32-point LED display (Lit when ON, SW selection)			
External c	connection method		Connector connection (Compliant with the MIL standard, 40P, two pieces used)			

#### Analog input unit Specifications

Item

No. of input points

Input range (resolution)	Voltage	-5 to +5 V DC (Resolution: 1/64,000) 0 to +5 V DC (Resolution: 1/32,000) +1 to +5 V DC (Resolution: 1/25,600) (Note 1)		
	Current	0 to + 20 mA (Resolution: 1/32,000) +4 to + 20 mA (Resolution: 1/25,600) (Note 1)		
Conversion speed		50 μs/ch		
Exceeding the rated ran	ge	Possible to output up to the rated value ± 2%. With the 0 to 20 mA range, the lower limit is not supported for exceeding the rated range. (Note 2)		
Total accuracy		±0.2 %F.S. or less (at +25 °C) ±0.4 %F.S. or less (at 0 to +55 °C)		
Input impedance		Voltage input: Approximately 1 M $\Omega$ ; current input: Approximately 250 $\Omega$		
Absolute max. input		Voltage input: Approximately -15 V to +15 V; current input: Approximately -30 mA to +30 mA		
Insulation method		Between input terminals and internal circuit: Photocoupler and isolated DC/DC converter Between channels: Non-insulated		
Execution / Non-execution	on channel settings	Possible to make non-converted channel settings.		
Input range selection		Possible to make settings on a channel-by-channel basis.		
	Number of averaging times	Setting range of 2 to 60,000 times		
Average processing	Time average	Time setting range of 1 to 1,500 ms		
	Moving average	Setting range of 2 to 2,000 times		
Offset / Gain settings		A desired value within the digital output range can be set for the offset value.  Setting range: -3000 to +3000  A desired value within the digital output range can be set for the gain value.  Setting range: +9000 to +11000 (90 % to 110 %)		
Scale conversion settings		A desired value within the digital output range can be set for the scale conversion setting value. Setting range: -32768 to +32767		
Upper limit / lower limit o	comparison	Output if the value is outside the preset upper limit or lower limit.		

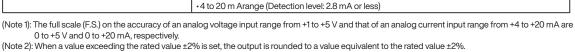
Setting range: -32768 to +32767

Holding max. / min. values sampled

-10 to +10 V DC (Resolution: 1/64,000) 0 to +10 V DC (Resolution: 1/32,000)

Specifications

8ch



•1 to 5 V range (Detection level: 0.7 V or less)

 $Disconnection \ detection \ is \ possible \ for \ the \ following \ ranges. \ Possible \ to \ select \ auto \ or \ manual \ resetting.$ 

#### Analog output unit Specifications

Upper limit / lower limit comparison

Max. / Min. hold

Disconnection detection

Item		Specifications			
No. of output points		4 ch			
Output range (resolution) (Note 1)	Voltage	-10 to +10 V DC (Resolution: 1/64,000) 0 to +10 V DC (Resolution: 1/32,000) -5 to +5 V DC (Resolution: 1/64,000) 0 to +5 V DC (Resolution: 1/32,000) +1 to +5 V DC (Resolution: 1/32,600)			
	Current	0 to +20 mA(Resolution: 1/32,000) +4 to +20 mA (Resolution: 1/25,600)			
Conversion speed		50 μs/4 ch			
Exceeding the rated ran	ge	Possible to output up to the rated value ± 2%.  With the 0 to 20 mA range, the lower limit is not supported for exceeding the rated range. (Note 2)			
Total accuracy		±0.2 %F.S. or less (at +25 °C) ±0.4 %F.S. or less (at 0 to +55 °C)			
Output impedance (volt	age output)	$0.5\Omega$ or less			
Maximum output curren	t (voltage output)	10 mA			
Output allowable load res	istance (current output)	500 Ω or less			
Insulation method		Between output terminals and internal circuit: Photocoupler and isolated DC/DC converter Between channels: Non-insulated			
Execution / Non-execution	on channel settings	Possible to make non-converted channel settings.			
Clipping function		Upper and lower output limits can be set for digital input values. Setting range: -32,640 to +32,640			
Scale conversion settings		A desired value within the digital input range can be set for the scale conversion setting value. Setting range: -32768 to +32767			
Offset / Gain settings		A desired value within the digital input range can be set for the offset value.  Setting range: -3,000 to +3,000  A desired value within the digital input range can be set for the gain value.  Setting range: +9000 to +11000 (90 % to 110 %)			
Analog output hold (in S	TOP mode)	A desired output value while in STOP mode can be set as a digital value. Setting range: -32640 to +32640			



AGM1AD8

AGM1DA4

(Note 1): The full scale (F.S.) on the accuracy of an analog voltage output range from +1 to +5 V and that of an analog current output range from +4 to +20 mA are 0 to +5 V and 0 to +20 mA, respectively. (Note 2): When a value exceeding the rated value ±2% is set, the output is rounded to a value equivalent to the rated value ±2%.

## **Specifications**

#### Performance Specifications of the Pulse Output Unit



Item		Specifications				
Product No.		AGM1PG04T	AGM1PG04L			
Output type		Transistor	Line driver			
Number of control axe	s	4 axis, independent	•			
	Command unit	Pulse unit (for increment or absolute)				
Position command	Max. pulse count	Signed 32 bits (-2,147,483,648 to +2,147,483,647 pulses)				
		1pps to 500 kpps	1 pps to 4 Mpps			
Speed command	Command range	(can be set in 1 pps.)	(can be set in 1 pps.)			
Acceleration /	Acceleration / deceleration method	Linear acceleration / deceleration, S-shaped acc	eleration / deceleration control			
deceleration command	S-shape pattern	Sine curve, Cubic curve (can be select)				
	Home return speed	Speed setting possible (changes return speed and search speed)				
Home return	Input signal	Home input, near home input, over limit input (+), over limit input (-)				
	Output signal	Deviation counter clear signal				
Operation mode		E-point control (Linear and S-shaped acceleration / deceleration)     P-point control (Linear and S-shaped acceleration / deceleration)     Home return (Home search)     JOG operation (Note 1)     JOG positioning     Pulser input operation (Note 2)     Transfer multiplication ratio (×1, ×2, ×5, ×10, ×50, ×100, ×500, ×1000)     Real-time frequency change function				
Startup time		0.001 ms / 0.005 ms / 0.02 ms				
Output interface	Output mode	Pulse/Sign, CW/CCW				
	Counting range	Signed 32 bits (-2,147,483,648 to +2,147,483,647 p	oulses)			
Feedback counter	Input mode	2-phase input, direction identification input, individual input (transfer multiple available for each mode)				
function (Note 2)	Management	4 MHz (2-phase input)				
	Max. counting speed	1MHz (Direction distinction input and individual input)				
Other functions		Built-in over limit input (+) and over limit input (-) Servo ON output incorporated				

•Servo ON output incorporated  $(Note 1): When \ Linear \ acceleration/deceleration \ operation \ is \ selected, the \ target \ speed \ can \ be \ changed \ during \ an \ operation.$ (Note 2): "Pulser input operation" and "Feedback counter" use the same pulse input terminal. Either function of the two can only be used.

#### List of consumption current

Unit type		Consumption current
GM1 controller RTEX type	AGM1CSRX16T	400 mA or less
ON 44 a particular (Table of OAT & to a	AGM1CSEC16T	400 mA or less
GM1 controller EtherCAT type	AGM1CSEC16P	400 mA or less
	AGM1X64D2	90 mA or less
	AGM1Y64T	160 mA or less
Input / output unit	AGM1Y64P	160 mA or less
	AGM1XY64D2T	120 mA or less
	AGM1XY64D2P	120 mA or less
Analog input / output unit	AGM1AD8	130 mA or less
Analog input / output unit	AGM1DA4	160 mA or less
Dulgo output unit	AGM1PG04T	100 mA or less
Pulse output unit	AGM1PG04L	100 mA or less

## **Product types**

#### Controller

Product name	Number of axes	Network	Number of I/O	High-speed counter	Rated voltage	Output specifications	Part No.								
GM1 controller	16 axes	RTEX	Input: 16 points				AGM1CSRX16T								
Ada William	22 0 0 0	Ethor CAT		16 points	16 points	16 points	16 points	16 points	16 points		16 points	16 points	2 ch	24 V DC	Transistor output sink(NPN)
	32 axes	EtherCAT	points			Transistor output sauce(PNP)	AGM1CSEC16P *2								

#### Input / output unit

Product name	Туре	Number of I/O	Specifications	Part No.
Input / output unit	DC input	Input: 64 points	24 V DC 32 points/1 common	AGM1X64D2
	Transistor output sink(NPN)	Output:	Maximum load current: 0.3 A (20.4 to 26.4 V DC),	AGM1Y64T
uiiiin	Transistor output sauce(PNP)		30 mA (4.75 V DC) 3.2 A/common 32 points/1 common	AGM1Y64P *2
	DC input Transistor output sink(NPN)	Input: 32 points	Input: 24 V DC 32 points/1 common Output: Maximum load current: 0.3 A (20.4 to 26.4 V	AGM1XY64D2T
	DC input Transistor output sauce(PNP)	Output: 32 points	DC), 30 mA (4.75 V DC) 3.2 A/common 32 points/1 common	AGM1XY64D2P *2

#### Analog input / output unit

Product name	Specifications	Number of channels	Part No.
Analog input unit	Conversion speed 50 µs/ch Resolution 16 bit (maximum) Accuracy ±0.2 %F.S. or less (at+25 °C)	8 ch	AGM1AD8
Analog output unit	Conversion speed 50 µs/4 ch Resolution 16 bit (maximum Accuracy ±0.2 %F.S. or less (at+25 °C)	4 ch	AGM1DA4

#### Pulse output unit

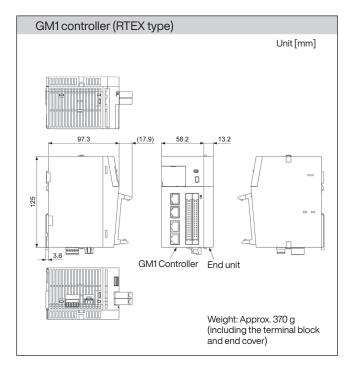
Product name	Output type	Number of control axes	Speed command	Part No.	
Pulse output unit					
III	Transistor	4 axes	1 pps to 500 kpps	AGM1PG04T	
	Line driver	4 axes	1 pps to 4 Mpps	AGM1PG04L	

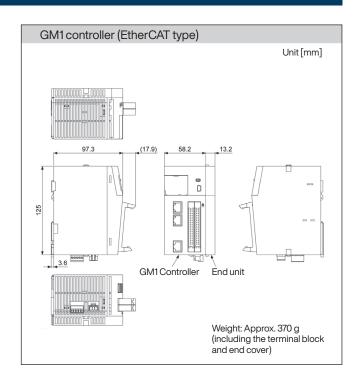
#### Option

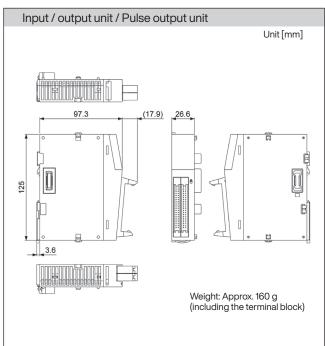
Product name	Description	Part No.
Discrete-wire connector set (40-pin)	For GM1 Controller, for Expansion Unit (2 pieces)	AFP2801
Flat cable connector set (40-pin)	Use for batch wiring with flat cable For GM1 Controller, for Expansion Unit (2 pieces)	AFP2802

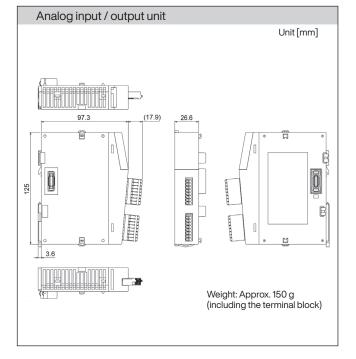
<sup>\*1</sup> Connectors are not included with the controller or expansion unit. Please ensure you have the following connectors. Discrete-wire connector set (Part No.: AFP2801) Flat cable connector set (Part No.: AFP2802) Power cable (Part No.: AFPG805) is included with the controller.
\*2 Excluded from KC marking.

## **Dimensions**



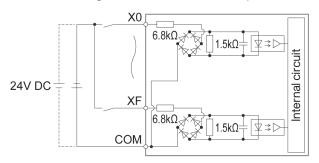




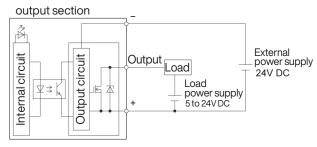


## **Circuit Diagram**

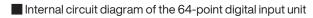
■ Internal circuit diagram of the GM1 Controller input section

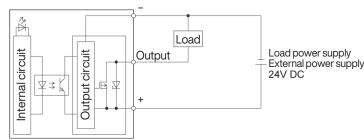


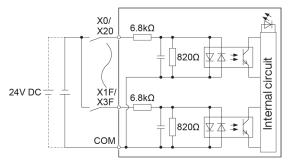
■ Internal circuit diagram of the GM1 Controller (sink type)



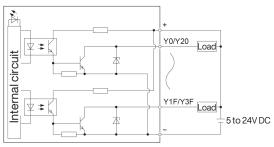
■ Internal circuit diagram of the GM1 Controller output section



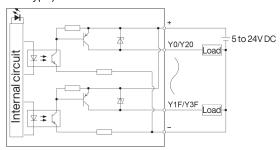




■ Internal circuit diagram of the 64-point digital output unit (sink type)

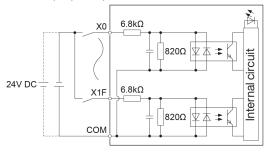


■ Internal circuit diagram of the 64-point digital output unit (source type)

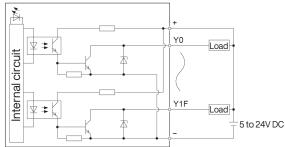


Internal circuit diagram of the 64-point digital input / output unit (sink type)



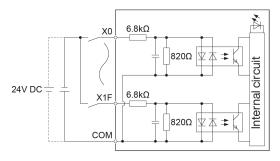


Output section (32 points)

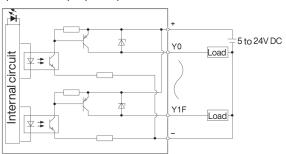


Internal circuit diagram of the 64-point digital input / output unit (source type)

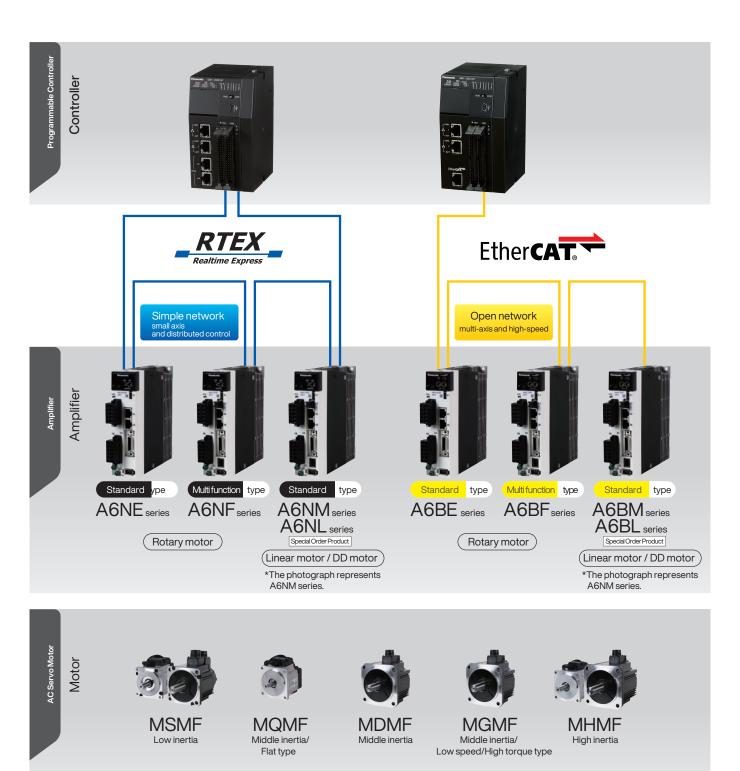
Input section (32 points)



Output section (32 points)



# A6 Family



Special Order Product For more information, visit the website or please request to our distributors separately.

#### **Motor Line-up**

	M	lotor	Rated output (kW)	Rated rotational speed (Max. speed) (r/min)	Rotary encoder 23 bit absolute	Enclosure	Motor lead-out configuration	Features	Applications											
		80 mm sq. or less	0.05 0.1 0.2 0.4 0.75 1.0	3000 (6000)	0	IP65	Leadwire	<ul><li>Small capacity</li><li>Suitable for high speed application</li></ul>	<ul><li>Bonder</li><li>Semiconductor</li><li>production</li></ul>											
Low inertia	MSMF		0.05 0.1 0.2 0.4 0.75 1.0	3000 (6000)	0	IP67	Connector	Suitable for all applications	equipment • Packing machines etc											
			1.0 1.5 2.0 3.0	3000 (5000)				Middle capacity     Suitable for the machines directly	• SMT machines • Food											
		100 mm sq. or more	4.0 5.0	3000 (4500)	0	IP67	Connector	coupled with ball screw and high stiffness and high repetitive application	machines • LCD production equipment etc											
	MQMF	80 mm sq. or less	0.1 0.2	3000 (6500)	0	IP65	Leadwire	Small capacity     Flat type and suitable for low stiffness machines with belt	• SMT machines • Inserter machines											
inertia	(Flat type)	80 mm sq. or less	0.1 0.2	3000 (6500)	0	IP67	Connector	driven  • Motors with gear reducers are also available.	<ul><li>Belt drive machines</li><li>unloading robot</li></ul>											
Middle	Middle inertia	130 mm sq. or more												1.0 1.5 2.0 3.0 4.0 5.0	2000 (3000)		IP67	Connector	Middle capacity     Suitable for low	• Conveyors • Robots
	MDMF		7.5 11.0 15.0	1500 (3000) 1500 (2000)	0		( 22.0 kW (: Terminal)	stiffness machines with belt driven	Machine tool etc											
	MGMF (Low speed/ High torque type	130 mm sq. or more	22.0  0.85 1.3  1.8 2.4  2.9 4.4  5.5	1500 (3000)	0	IP67	Connector	Middle capacity     Suitable for low speed and high torque application	Conveyors     Robots     Textile     machines     etc											
			0.05 0.1 0.2 0.4 0.75 1.0	3000 (6500) 3000	0	IP65	Leadwire	Small capacity     Suitable for low     stiffness machines	• Conveyors											
High inertia	High inertia	80 mm sq. or less	0.05 0.1 0.2 0.4	(6000) 3000 (6500) 3000	0	IP67	Connector	with belt driven  Motors with gear reducers are also available.	Robots     etc											
		80 mm sq. or less	0.75 1.0 1.0 1.5 2.0 3.0 4.0 5.0	(6000) 2000 (3000)	0	IP67	Connector	Middle capacity     Suitable for low stiffness machines with belt driven, and	Conveyors     Robots     LCD man- ufacturing											
		130 mm sq. or more	7.5	1500 (3000)				large load moment of inertia	equipment etc											

#### **Panasonic NETWORK MOTION**

#### **NETWORK MOTION**

	GM1	FP0H	FP-XH M8N
Controller			
Network	RTEX EtherCAT	RTEX	RTEX
Corresponding AC servomotor	MINAS-A6N / A5N MINAS-A6B / A5B	MINAS-A6N / A5N	MINAS-A6N / A5N
Maximum number of sync axes	RTEX 16 axes EtherCAT 32 axes	4/8 axes	8 axes
Command update period (Max.)	500 µs	1ms	1ms
Operation command	position / speed / torque	position	position
Interpolation control	Straight line / Arc / Spiral	Straight line / Arc / Spiral	Straight line / Arc / Spiral
Synchronization command	Cam synchronization, Gear synchronization, CNC control	Synchronization, Electronic cam, Electronic clutch, Electronic gear	Synchronization, Electronic cam, Electronic clutch, Electronic gear
Tool	GM Programmer	Control FPWIN GR7 Control FPWIN Pro7	Control FPWIN GR7 Control FPWIN Pro7
Ethernet Port	2 port *IP address can be set for each port	2 port *Only one IP address can be set	none
Communication protocol (Ethernet)	OPC UA, Ethernet / IP, Modbus-TCP, CodesysV3	Ethernet / P, Modbus-TCP, MC protocol	
FTP server function	0	0	
System scale	Large		Small

## Safety Precautions

• Before you use the product, please carefully read through the instruction manual, the installation instructions and the manuals, and understand them in detail to use the product properly.

Please contact .....

Panasonic Industry Co., Ltd. **Industrial Device Business Division** 

7-1-1 Morofuku, Daito City, Osaka, 574-0844, Japan industrial.panasonic.com/ac/e/



Q Panasonic Industrial

Search



Specifications are subject to change without notice.